Art Unit: Not Yet Assigned Page 3

Amendments to the Claims:

This listing of claims replaces all prior versions, and listings, of claims in this application.

Listing of Claims:

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1. (Original) A method for determining at least one process parameter, the method comprising:

obtaining calibration measurement data from a plurality of calibration marker structure sets provided on a calibration object, each of said plurality of calibration marker structure sets comprising at least one calibration marker structure, calibration marker structures of different calibration marker structure sets being created using different known values of said at least one process parameter;

determining a mathematical model by using said known values of said at least one process parameter and by employing a regression technique on said calibration measurement data, said mathematical model comprising a number of regression coefficients;

obtaining measurement data from at least one marker structure provided on an object, said at least one marker structure being made using an unknown value of said at least one process parameter; and

determining the unknown value of said at least one process parameter for said object from said obtained measurement data by employing said regression coefficients of said mathematical model.

- 2. (Currently Amended) Method The method according to claim 1, wherein said calibration measurement data and said measurement data are obtained with an optical detector.
- 3. (Currently Amended) Method The method according to claim 2, wherein said optical detector is a scatterometer.

Art Unit: Not Yet Assigned Page 4

4. (Currently Amended) Method The method according to any of the preceding elaims claim 1, wherein the regression technique used by the mathematical model is selected from a group consisting of principal component regression, non-linear principal component regression, partial least squares modeling and non-linear partial least squares modeling.

- 5. (Currently Amended) Method The method according to any of the preceding elaims claim 1, wherein said object is a substrate.
- 6. (Currently Amended) Method The method according to claim 5, wherein the substrate comprises one of a group consisting of a test wafer and a product wafer.
- 7. (Currently Amended) Method The method according to claim 5 or 6, wherein the at least one marker structure is positioned on said substrate within one of the group consisting of a chip area and a scribe-lane.
- 8. (Currently Amended) Method The method according to claim 7, wherein the at least one marker structure is a part of a device pattern within a chip area.
- 9. (Currently Amended) Method The method according to any of the preceding elaims claim 1, wherein the at least one marker structure comprises a diffraction grating.
- 10. (Currently Amended) Method The method according to any of the preceding elaims claim 1, wherein the method further comprises preprocessing the obtained calibration measurement data and the obtained measurement data before said employing said regression coefficients.
- 11. (Currently Amended) Method The method according to claim 10, wherein said preprocessing comprises performing on said data at least one of the group of mathematical

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Art Unit: Not Yet Assigned Page 5

operations consisting of subtraction of a mean, division by standard deviation, selection of optical parameters and weighing of optical parameters, and

wherein the optical parameters comprise at least one of the group of parameters consisting of wavelength, angle and polarization state.

- 12. (Currently Amended) Method The method according to any of the preceding claims claim 1 wherein each of said plurality of calibration marker structure sets comprises at least a first and a different second calibration marker structure.
- 13. (Currently Amended) Method The method according to claim 12, wherein said first calibration marker structure comprises a number of non-patterned layers and said second calibration marker structure comprises the same non-patterned layers on top of which a pattern is provided.
- 14. (Currently Amended) Method The method according to claim 12 or 13, wherein said first calibration marker structure comprises a pattern with isolated lines and said second calibration marker structure comprises a pattern with dense lines or isolated spaces.
- 15. (Currently Amended) Method The method according to any of the claims claim 12-14, wherein the first and second calibration marker structures are in close proximity to each other, such that a distance between the first and second calibration marker structure is in the same order of magnitude as a size of the first and second calibration marker structure.
- 16. (Currently Amended) Method The method according to any of preceding claims claim 1, wherein at least one calibration structure within a calibration marker structure set and said marker structure have substantially comparable shapes.

Art Unit: Not Yet Assigned Page 6

17. (Currently Amended) Method The method according to any of the preceding elaims claim 1, wherein said calibration data and measurement data comprise spectral data.

- 18. (Currently Amended) Method The method according to any of the preceding claims claim 1, wherein said method is related to at least one of a lithographic apparatus and a track.
- 19. (Currently Amended) Method The method according to claim 18, wherein said at least one process parameter is selected from a group consisting of focus, exposure dose, overlay error, track parameters related to dose, variation of line width over reticle, variations from reticle-to-reticle, projection lens aberrations, projection lens flare, and angular distribution of light illuminating the reticle.
- 20. (Currently Amended) Method The method according to claim 18 or 19, wherein the lithographic apparatus comprises:
 - an illumination system configured to provide a beam of radiation;
- a support structure configured to support a patterning structure, the patterning structure serving to impart the beam of radiation with a pattern in its cross-section;
 - a substrate table configured to hold a substrate; and
- a projection system configured to project the patterned beam onto a target portion of the substrate.
 - 21. (Cancelled).
- 22. (Original) A system for determining at least one process parameter, the system comprising:
- a detector arranged to obtain calibration measurement data from a plurality of calibration marker structure sets provided on a calibration object, each of said plurality of calibration marker structure sets comprising at least one calibration marker structure, calibration

Attorney's Docket No.: 081468-0356680 Serial No.: New Application Page 7

Art Unit: Not Yet Assigned

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marker structures of different calibration marker structure sets being created using different known values of said at least one process parameter;

a processor unit storing a mathematical model determined by using said known values of said at least one process parameter and by employing a regression technique on said calibration measurement data, said mathematical model comprising a number of regression coefficients:

said processor unit being arranged to obtain measurement data from at least one marker structure provided on an object, said at least one marker structure being made using an unknown value of said at least one process parameter; and to determine the unknown value of said at least one process parameter for said object from said obtained measurement data by employing said regression coefficients of said mathematical model.

- (Currently Amended) System The system according to claim 22, wherein said 23. detector is an optical detector.
- (Currently Amended) System The system according to claim 23, wherein said 24. optical detector is a scatterometer.
- (Currently Amended) System The system according to any of the claims 22-24 25. claim 22, wherein the regression technique used by the mathematical model is selected from a group consisting of principal component regression, non-linear principal component regression, partial least squares modeling and non-linear partial least squares modeling.
- (Currently Amended) System The system according to any of the claims 22-25 26. claim 22, wherein said object is a substrate.
- (Currently Amended) System The system according to claim 26, wherein the 27. substrate comprises one of a group consisting of a test wafer and a product wafer.

Art Unit: Not Yet Assigned Page 8

28. (Currently Amended) System The system according to claim 26 or 27, wherein the at least one marker structure is positioned on said substrate within one of the group consisting of a chip area and a scribe-lane.

- 29. (Currently Amended) System The system according to claim 28, wherein the at least one marker structure is a part of a device pattern within a chip area.
- 30. (Currently Amended) System The system according to any of the claims 22-29 claim 22, wherein the at least one marker structure comprises a diffraction grating.
- 31. (Currently Amended) System The system according to any of the claims 22-30 claim 22, wherein the processor unit is arranged to preprocess the obtained measurement data before said employing said regression coefficients.
- 32. (Currently Amended) System The system according to claim 31, wherein said preprocessing comprises performing on said data at least one of the group of mathematical operations consisting of subtraction of a mean, division by standard deviation, selection of optical parameters and weighing of optical parameters, and

wherein the optical parameters comprise at least one of the group of parameters consisting of wavelength, angle and polarization state.

- 33. (Currently Amended) System The system according to any of the claims 22-32 claim 22 wherein each of said plurality of calibration marker structure sets comprises at least a first and a different second calibration marker structure.
- 34. (Currently Amended) System The system according to claim 33, wherein said first calibration marker structure comprises a number of non-patterned layers and said second

Attorney's Docket No.: 081468-0356680 Serial No.: New Application Page 9

Art Unit: Not Yet Assigned

calibration marker structure comprises the same non-patterned layers on top of which a pattern is provided.

35. (Currently Amended) System The system according to claim 33 or 34, wherein said first calibration marker structure comprises a pattern with isolated lines and said second calibration marker structure comprises a pattern with dense lines or isolated spaces.

36. (Currently Amended) System The system according to any of the claims 33-35 claim 33, wherein the first and second calibration marker structures are in close proximity to each other, such that a distance between the first and second calibration marker structure is in the same order of magnitude as a size of the first and second calibration marker structure.

- 37. (Currently Amended) System The system according to any of claims 22-36 claim 22, wherein at least one calibration structure within a calibration marker structure set and said marker structure have substantially comparable shapes.
- 38. (Currently Amended) System The system according to any of the claims 22-37 claim 22, wherein said calibration data and measurement data comprise spectral data.
- 39. (Currently Amended) System The system according to any of the claims 22-38 claim 22, wherein said system comprises at least one of a lithographic apparatus and a track.
- 40. (Currently Amended) System The system according to claim 39, wherein said at least one process parameter is selected from a group consisting of focus, exposure dose, overlay error, track parameters related to dose, variation of line width over reticle, variations from reticle-to-reticle, projection lens aberrations, projection lens flare, and angular distribution of light illuminating the reticle.

Serial No.: New Application Attorney's Docket No.: 081468-0356680
Art Unit: Not Yet Assigned Page 10

41. (Currently Amended) System The system according to claim 39 or 40, comprising:

an illumination system configured to provide a beam of radiation;

a support structure configured to support a patterning structure, the patterning structure serving to impart the beam of radiation with a pattern in its cross-section;

a substrate table configured to hold a substrate; and

a projection system configured to project the patterned beam onto a target portion of the substrate.

42. (Cancelled).